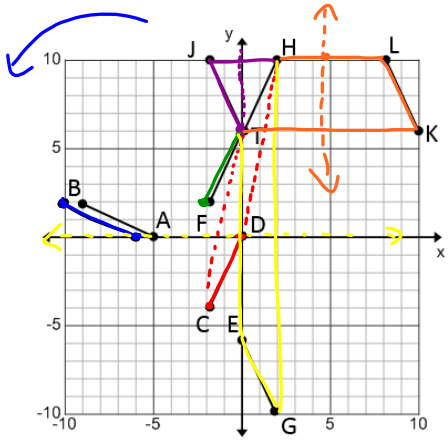
Agenda- 6.9

Rigid Motion on and off the Coordiante Plane

- Check HW 6.8
- Guided Notes 6.9

HW - Worksheet 6.9

Test - TUESDAY



Unit 6-9R & 6-12L Notes & Problem Set – Rigid Motions

REVIEW & EXPLORATION

Identify a single transformation that would map $\overline{TH}$ onto

i. $\overline{AB}$ ROTATION 90° AROUND ORIGIN

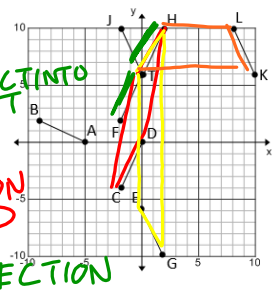
ii. $\overline{CD}$ TRANSLATION <-2, -10>

iii. $\overline{TF}$ ROTATION 180 AROUND T OR REFLECT INTO T

iv. $\overline{EG}$ REFLECT INTO X-AXIS

v. $\overline{TJ}$ REFLECT INTO Y-AXIS

vi. $\overline{KL}$ REFLECT INTO X-S



b. Which transformation(s) produced a parallelogram? TRANSLATION

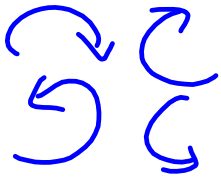
What happeded to the slope of the pre-image? PRESERVED

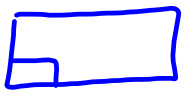
c. What other transformation(s) preserved slope? ROTATION 180° OR PT REFLECTION

d. Which transformstion(s) produced a trapezoid? REFLECT INTO LINE NOT ON SEGMENT

EXPLORING PARALLELISM AND PERPENDICULARITY THROUGH RIGID MOTION

Recall how we have mapped segments and polygons through rigid motions and found that both ∠ MEASURE and DISTANCE are preserved under translations, rotations, and reflections through the concepts of between-ness. Thus, the pre-image and image were congruent to each other, which means that these rigid motion transformations are ISOMETRY. Also remember that line reflections do not preserve orientation. Do any or all rigid motions preserve parallelism and perpendicularity?



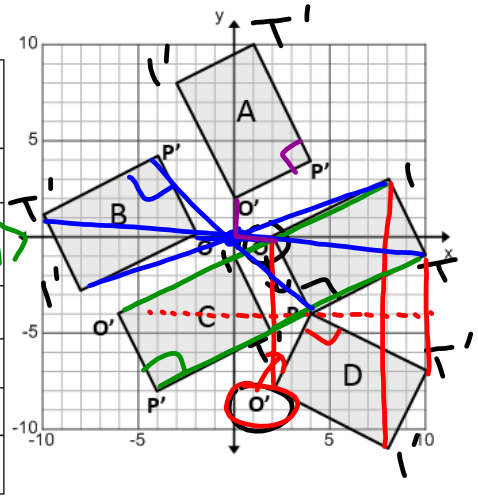


1) Given rectangle OPTI, determine which image is the result of each transformation of the pre-image. Then label the other corresponding vertices.

	Reflection into a line	Reflection into a point	Rotation around the origin	Translation
Which Image?	D	B	A	C
Details	y=-4	ORIGIN	90°	<8,-9>
$\overline{O'P'} \parallel \overline{T'I'}$?	YES	YES	YES	YES
$\overline{P'T'} \parallel \overline{I'O'}$?	YES	YES	YES	YES
$\overline{O'P'} \perp \overline{P'T'}$?	YES	YES	YES	YES
Was slope preserved?	NO	YES	NO	YES

II ISMS

LITY HRES



2) Use the properties of rigid motions to explain why each image O'P'T'I' is congruent to the pre-image OPTI.

TRANSLATION, REFLECTION INTO LINE OR POINT, OR A ROTATION PRESERVES ∠ MEASURE & DISTANCE.

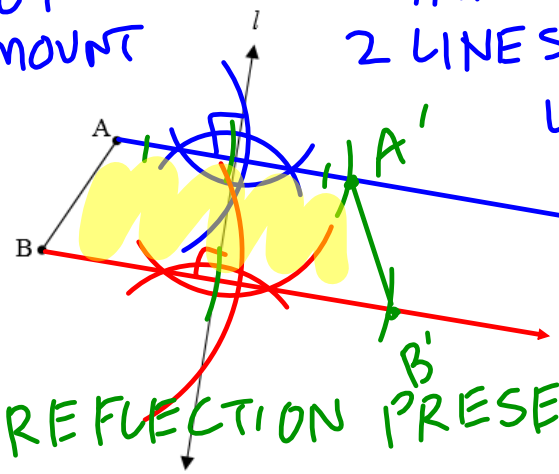
Planar Rigid Motions

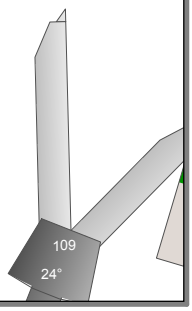
1. Using formal geometric construction skills, perform the transformation $r_{line\ l}(\overline{AB})$. Identify what type of quadrilateral ABB'A' is created and explain your reasoning.

⊥ IN & OUT SAME AMOUNT

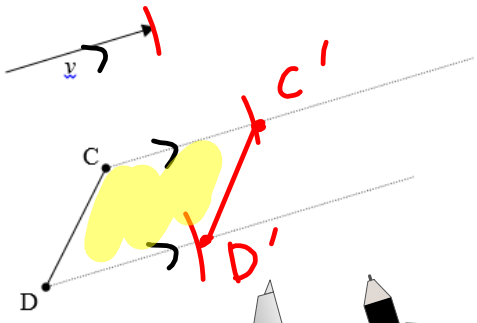
TRAPEZOID: $\overline{AA'} \parallel \overline{BB'}$ 2 LINES ⊥ TO SAME LINE ARE ∥.

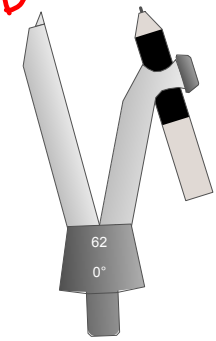
ISOS TRAP: LEGS $\overline{AB} \cong \overline{A'B'}$ B/C A REFLECTION PRESERVES DISTANCE.





2. Using formal geometric construction skills on the provided parallel segments, perform the transformation $T_{\vec{v}}(\overline{CD})$. Identify what type of quadrilateral CDD'C' is created and explain your reasoning.





CDD'C' ▱

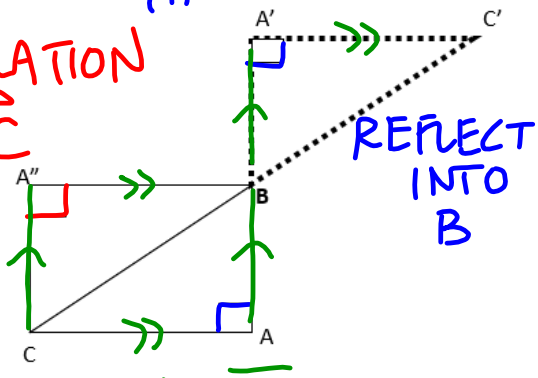
$\overline{CD} \cong \overline{C'D'}$ TRANSLATIONS PRESERVE DISTANCE & SLOPE

$\overline{CD} \parallel \overline{C'D'}$

3. Given right ΔABC, prove through a series of rigid motions that quadrilateral ABA"C is rectangle.

ROTATION 180° AROUND B

TRANSLATION $\overrightarrow{BC}$



REFLECT INTO B

RECT: 1 RT ∠

∠ MEAS PRESERVED UNDER ROTATION/TRANSL

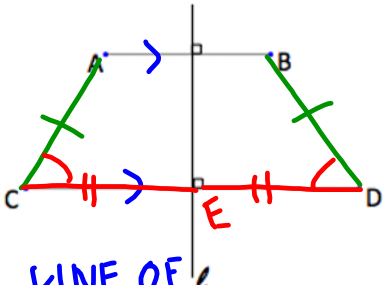
$\overline{AB} \parallel \overline{A"C}$

$\overline{AC} \parallel \overline{A"B}$

▱ : BOTH PAIRS OPPOSITE SIDES ∥

SLOPE IS PRESERVED UNDER ROT/TR (POINT RELECTION)

4. Given in the figure below, line l is the perpendicular bisector of $\overline{AB}$ and of $\overline{CD}$. Use a transformational approach to explain why:



LINE OF REFLECTION

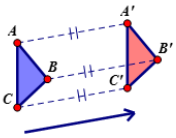
a. $\overline{AB} \parallel \overline{CD}$. 2 LINES ⊥ TO SAME LINE ARE ∥

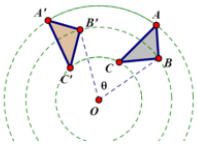
b. $\overline{AC} \cong \overline{BD}$ REFLECTION PRES DISTANCE

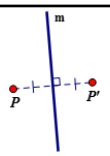
c. $\angle ACD \cong \angle BDC$. ∥ ∥ ∠ MEASURE

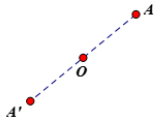
d. Quadrilateral ABDC is an isosceles trapezoid.

1 SET ∥ SIDES + ≅ LEGS









	Translation	Rotation	Reflection into Line	Reflection into Point / 180° Rotation
Angle Measure	✓	✓	✓	✓
Distance	✓	✓	✓	✓
Orientation	✓	✓	NO	✓
Parallelism	✓	✓	✓	✓
Perpendicularity	✓	✓	✓	✓
Slope	✓	NO	NO	✓
Invariant Points	NONE	IF VERTEX = CENTER OF ROTATION	IF ON LINE OF REFLECTION	IF CENTER OF ROTATION OR PT BEING REFLECTED INTO